## **Specifications**

## Trimble R780 GNSS Smart Antenna



Receiver Name R780 GNSS Smart Antenna

**Configuration Option** 

Base and Rover interchangeability

Yes, upgradeable to Rover, Base or Rover / Base

Rover position update rate 1 Hz, 2 Hz, 5 Hz, 10 Hz, 20 Hz

Rover maximum range from base radio

Unrestricted, typical range 2–5 km (1.2–3 miles) without radio repeater

Rover operation within a VRS™ network
Yes

Heading and Moving Base operation Yes - option[7]

Factory options GPS, GLONASS, Triple Frequency, Wi-Fi, Logging (9.5GB)

General

Keyboard and display LED indicators for satellite tracking, radio link status, WiFi and power monitoring

On/Off key for one-button startup

Dimensions (L × W × D) 13.9 cm (5.5 in) Diameter × 13 cm (5.1 in) including connectors

Weight 1.55 kg (3.42 lb) receiver only including radio and battery

Complete system (rover including controller and pole) 3.9 kg (8.6 lbs)

Temperature

Operating[1]  $-40 \, ^{\circ}\text{C to } +65 \, ^{\circ}\text{C } (-40 \, ^{\circ}\text{F to } +149 \, ^{\circ}\text{F})$ 

Storage  $-40~^{\circ}\text{C to +75 °C }(-40~^{\circ}\text{F to +167 °F})$ 

Humidity 100%, condensing

Ingress protection IP68 Certified per IEC-60529 - waterproof/dustproof (1m submersion for 1hr)

**Shock and Vibration** 

Pole drop Designed to survive a 2 m (6.6 ft) pole drop onto concrete

Shock – Non-operating 75 Gs at 6msec

Shock – Operating 40 Gs at 10msec

Vibration Mil-Std-810G, FIG 514.6E-1 Cat 24, Mil-Std-202G, FIG 214-1, Condition D

Measurements

Advanced Trimble Technology Custom GNSS chips

High-precision multiple correlator for GNSS pseudorange measurements

Unfiltered, unsmoothed pseudo-range measurements data for low noise, low multipath error, low-time domain correlation, and

high-dynamic response Very low noise carrier phase measurements with <1 mm precision

in a 1 Hz bandwidth

Trimble EVEREST+ multipath signal rejection

 ${\it MSS Band: CenterPoint RTX and OmniSTAR \ by \ subscription}$ 

Trimble xFill for short gaps in correction messages

GPS: L1 C/A, L1C, L2C, L5, L2E (Trimble method for tracking unencrypted L2P).

GLONASS: L1-C/A, L2-C/A, L1P, L2P, L3 Full Cycle Carrier

Upgrade to Galileo: E1, E5A, E5B & E5AltBOC[8]. Able to track E6.

BeiDou: B1,B1C,B2, B2A, B2B, B3 (Able to track 3rd generation BeiDou signals)

Integrated MEM's sensor for eBubble

4-channel SBAS L1 C/A, L5 (WAAS/EGNOS/MSAS/GAGAN)

QZSS: L1 C/A, L1C, L1 SAIF, L2C, L5

Able to track NavIC (IRNSS) L5-C/A

SBAS (WAAS/EGNOS/MSAS) Positioning[3]

Accuracy Horizontal ± 0.50m (1.6 ft), Vertical ± 0.85m (2.8 ft)

Code Differential GPS Positioning[2]

Horizontal accuracy 0.25 m + 1 ppm RMS (0.8 ft + 1 ppm RMS)

Vertical accuracy

OmniSTAR® Positioning

VBS service accuracy Horizontal <1 m (3.3 ft)

XP service accuracy

Horizontal 0.2 m (0.66 ft), Vertical 0.3 m (1.0 ft)

HP service accuracy

Horizontal 0.1 m (0.33 ft), Vertical 0.15 m (0.5 ft)

CenterPoint® RTX Positioning

Accuracy[12] Horizontal 2cm (0.06 ft) RMS, Vertical 5cm (0.16 ft) RMS

Convergence time for specified precisions[12] 5 minutes in select regions, and within 30 minutes worldwide

xFill Positioning

xFill accuracy RTK11 + 10mm(0.03 ft)/min Horiz. + 20mm(0.06 ft)/min Vert. RMS

**Location RTK Positioning** 

Horizontal accuracy Location RTK (10/10) or (10/2) 10 cm + 1 ppm RMS (0.32 ft + 1 ppm)

Vertical accuracy

Location RTK (10/10) 10 cm + 1 ppm RMS (0.32 ft + 1 ppm)

Location RTK (10/2) 2 cm + 1 ppm RMS (0.065 ft + 1 ppm)

Real-Time Kinematic (RTK up to 30 km) Positioning

[2]

Horizontal accuracy 8 mm + 1 ppm RMS (0.026 ft + 1 ppm RMS)

Vertical accuracy 15 mm + 1 ppm RMS (0.05 ft +1 ppm RMS)

Tilt Compensation (RTK, < 30° of tilt)[13]

Horizontal accuracy 8 mm RTK + 8 mm Tilt Compensation + 0.5 mm per degree of tilt + 1 ppm RMS (0.026 ft + 0.026 ft + 0.001 ft + 1 ppm RMS)

Vertical accuracy 15 mm + 1 ppm RMS (0.05 ft +1 ppm RMS)

Trimble VRS[9]

Horizontal accuracy 8 mm + 0.5 ppm RMS (0.026 ft +0.5 ppm)

Vertical accuracy 15 mm + 0.5 ppm RMS (0.05 ft +0.5 ppm)

Precise Heading

Heading accuracy When combined with R780[7]

2 m antenna separation 0.09° RMS

10 m antenna separation 0.05° RMS

**High Precision Static** 

Horizontal accuracy 3 mm + 0.1 ppm RMS (0.01 ft +0.1 ppm)

Vertical accuracy 3.5 mm + 0.4 ppm RMS (0.011 ft +0.4 ppm)

**Initialization Time** 

Regular RTK operation with base station Single/Multi-base

typically less than 8 seconds

0.50 m + 1 ppm RMS (1.6 ft + 1 ppm RMS)

Initialization reliability[4] >99.9%

Power

Internal Rechargeable, removable 7.4 V, 2.8 Ah Lithium-ion battery in internal battery compartment

Internal battery operates as a UPS during an ext power source failure

Internal battery will charge from external power source as long as source can support the power drain and is more than 11.8

Integrated charging circuitry.

Lithium-ion battery pack is rated for +45C. Ambient should not exceed +35C during charging or discharging.

Power

Power consumption

External External power input with over-voltage protection on Port 1 (7-pin Lemo 2-key). Minimum 10.8 V, Maximum 28 VDC, shutdown

optmized for 12V lead acid battery operation

Power source supply (Internal/External) is hot-swap capable in the event of power source removal or cut off

DC external power input with over-voltage protection on Port 1 (Lemo)

Receiver automatically turns on when connected to external power

3.2 W in rover mode with internal receive radio

5.2 W in base mode with internal 0.5 W transmit radio

Operation Time on Internal Battery [14]

Rover Approximately 5.5 hours; varies with temperature

Base station 450 MHz systems Approximately 4 hours; varies with temperature[5] 900 MHz systems Approximately 4 hours; varies with temperature **Regulatory Approvals** FCC Part 15 Subpart B (Class B Device), Part 15.247, Part 90 Canadian ICES-003. Cet appareil numérique de la classe B est conforme à la norme NMB-003 du Canada. Canadian RSS-310, RSS-210, and RSS-119. Cet appareil est conforme à la norme CNR-310, CNR-210, et CNR-119 du Canada. IEC 60950-1 2nd Edition CISPR 32, EN 55032, EN55024 RCM mark, ANS/NZS 4768 Radio Equipment Directive (RED 2014/53/EU) Japan MIC CE mark RoHS compliance WEEE compliance Communications Lemo (Serial 1) 7-pin Lemo 2-key, Power Input, USB. Optional USB to RS232 serial cable. Receiver supports RNDIS communications over USB 1PPS (1 Pulse-per-second) N/A Ethernet N/A WiFi Client or Access Point. Receive or transmit corrections. WiFi b/g Bluetooth wireless technology Fully-integrated, sealed 2.4 GHz Bluetooth module[6]. Integrated radios (optional) Fully-integrated, fully-sealed internal 403-473 MHz; Internal 900 MHz; Rx/Tx Channel spacing (450 MHz) 12.5 kHz or 25 kHz spacing available Sensitivity (450 MHz) -114 dBm (12 dB SINAD) 450 MHz output power 0.5 W. 2W 900 MHz output power 1.0 W Frequency approvals (902-928 MHz) USA/Canada External GSM/GPRS, cell phone support Supported for direct-dial and Internet-based correction streams using the Siteworks software Cell phone or GSM/GPRS modem inside external controller 1 Hz, 2 Hz, 5 Hz, 10 Hz, and 20 Hz positioning Receiver position update rate Correction data input CMR™, CMR+™, CMRx™, RTCM 2.x, RTCM 3 (require Rover upgrade) Correction data output CMR, CMR+, CMRx, RTCM 2.x, RTCM 3 (require Base upgrade) NMEA, GSOF Data outputs Features & Upgrades Standard Options GPS, GLONASS, Triple Frequency, Wi-Fi, Logging (9.5GB Internal) Precise Rover, Premium Precise Rover Precision upgrades Precise Base, Premium Precise Base, Premium Precise Base & Rover GALILEO, BeiDou Signal / Constellation upgrades [10] Feature upgrades IMU Notes 1 Receiver will operate normally to those temperature limits. Internal batteries will operate from: -20°C to +45°C when the battery is charged from an external dc supply. -20°C to +48°C when the device is powered by the battery pack. -20°C to +50°C when the device is powered by an external dc supply and the battery is fully charged (at maximum capacity). 2 Accuracy and reliability may be subject to anomalies such as multipath, obstructions, satellite geometry, interference and atmospheric conditions. Always follow recommended survey practices. 3 Depends on SBAS system performance. 4 May be affected by atmospheric conditions, signal multipath, and satellite geometry. Initialization reliability is continuously monitored to ensure highest quality 5 If your receiver is transmitting 2.0 W (450 MHz), you will experience reduced battery performance compared to the 0.5 W

6 Bluetooth type approvals are country specific. For more information, contact your local Trimble office or representative.

7 When receiver is combined with another suitable GNSS receiver.

8 Galileo Commercial Authorization

Developed under a Licence of the European Union and the European Space Agency. 9 Networked RTK PPM values are referenced to the closest physical base station

10 This Trimble SPS Receiver is capable of supporting existing and planned GNSS satellite signals, including GPS, GLONASS, GALILEO, BeiDou and QZSS, and existing and planned augmentations to these GNSS systems. 11 RTK refers to the last reported precision before the correction source was lost and xFill started

12 Receiver accuracy and convergence time varies based on GNSS constellation health, level of multipath, and proximity to obstructions such as large trees and buildings.

13 Proper survey techniques should be followed to reduce multipath error and maintain a good line of sight to the sky for satellite tracking. At greater than 30° of tilt, accuracy at the rod tip may decrease more than specified. The plumb pole routine needs to be performed without a quick release to obtain specified accuracies.

14 Using a new 2700 mAh battery.

Specifications subject to change without notice.

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